



## Main Motor Data Sheet and Curve

Purging for motor is not acceptable.

PURCHASER'S COMMENT/APPROVAL STATUS						Purchaser: NARGAN
1	AP: Approved (Released for Manufacturing)					
2	AN: Approved With Minor Comments (Fabrication may Proceed)					
3	NF: Approved With Comments (Fabrication not Proceed)					
	RJ: Rejected					Item No. (Tag No.): PK-6101
5	NR: Not be Returned					
Date:	29.08.2022	Signature:	A.AB			Vendor Doc. No.: DPIC9812-000-VD-1002-ME-DS-0042
D2	20-July-22	IFA	P.Sh	E.S	N.S	
D1	21-Feb-22	IFA	NA.PR	M.M	A.V	
D0	23-Jan-22	IFA	NA.PR	M.M	A.V	
<b>REV.</b>	<b>DATE ISSUE</b>	<b>Purpose of Issue</b>	<b>PREPARED</b>	<b>CHECKED</b>	<b>APPROVED</b>	



**Dehdasht Petrochemical Industry Company  
DEHDASHT HIGH DENSITY POLYETHYLENE PROJECT**



**DOCUMENT TITLE: MV MOTOR Data Sheet FOR  
ZONE 2 + H2 PRESENCE**

**Class: A  
Rev. No.: D2**

**Contract No.: DPIC/98-12**




**DOCUMENT NUMBER: DPIC9812-000-VD-1002-ME-DS-0042**

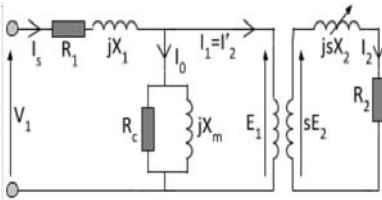
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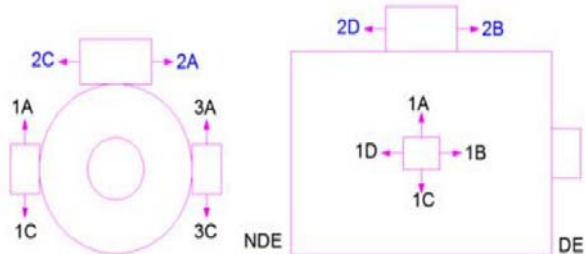





 	<b>Dehdasht Petrochemical Industry Company</b> <b>DEHDASHT HIGH DENSITY POLYETHYLENE PROJECT</b>	
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<b>D: PROTECTION FOR HAZARDOUS LOCATIONS DUE TO DUSTS (Note 3)</b>			
1	ZONE: [ ] ZONE 20	[ ] ZONE 21	[ ] ZONE 22
2	TYPE OF DUSTS: [ ] CONDUCTIVE	[ ] NON CONDUCTIVE	REFER TO :TM 751.1
3	EQUIPMENT CATEGORY: [ ] 1D	[ ] 2D	[ ] 3D
4	TYPE OF PROTECTION: [ ] Ex-tD	[ ] Ex-pD	SURFACE TEMPERATURE (Tmax.): .....°C
<b>E: NETWORK CHARACTERISTICS</b>			
1	SHORT CIRCUIT CURRENT, R.M.S : 25 /1 kA / s	SHORT CIRCUIT CURRENT, PEAK:	kA
2	NEUTRAL STATUS [ ] SOLIDLY EARTHED	[ X ] EARTHED THROUGH RESISTOR	[ ] INSULATED
<b>F: MOTOR OPERATING CHARACTERISTICS AND PARAMETERS</b>			
1	RATED SPEED: <b>2984</b> RPM	STARTING TORQUE: (Note 22) <b>0,6</b> Nm	
2	CONTINUOUS VARIABLE SPEED FROM/TO <b>N/A</b>	BREAK-DOWN TORQUE: <b>2.50</b> Nm	
3	FULL LOAD AMPERE: <b>150</b> A	SLIP AT FULL LOAD:	
4	FULL LOAD TORQUE: <b>4289</b> Nm	PULL-UP TORQUE (AT RATED VOLTAGE): <b>0.59</b> %	
5	STARTING CURRENT: (Note 4) <b>5,5 x FLA (550% In)</b>	OPEN CIRCUIT TIME CONSTANT:	S
6	STARTING TIME AT FULL LOAD: <b>3</b> S	<b>SYSTEM EARTHING: Grounded trough Resistance</b>	
7	NO LOAD CURRENT: A	Min. GROUNDING CONDUCTOR:	
8	SERVICE FACTOR: (Note 5) <b>1</b>	<b>THERMAL TIME CONSTANT</b> .....	
9	NOISE PRESSURE LEVEL AT 1 m: <b>78+3</b> dB(A) ≤ 82	COOLING: <b>176</b> min	
10	NUMBER OF STARTS PER HOUR:LOAD % <b>100 80</b>	HEATING:	min
11	COLD: <b>3</b>		
12	HOT: <b>2</b>	<b>CURVES REQUIRED BASED ON MOTOR SATURATION AT RATED V.</b>	
13	INERTIA CONSTANT (H): <b>0.52</b>	[ X ] SPEED VS TORQUE(ALSO AT <b>80%</b> RATED VOLTAGE)	
14	MOMENT OF INERTIA: <b>16,0</b> kg*m <sup>2</sup>	[ ] SPEED VS POWER FACTOR	
15	IMPEDANCE/PHASE: OHM Ucc%	[ X ] SPEED VS CURRENT (ALSO AT <b>80%</b> RATED VOLTAGE)	
16	ROTOR CLASS	TIME-CURRENT HEATING CURVE: <b>YES</b>	
17	AC STATOR RESISTANCE: .....OHM AT.....°C		
18	<b>REACTANCE AND EQUIVALENT CIRCUIT PARAMETERS :</b>	<b>DIMENSIONS:</b>	
19	SUB TRANSIENT (X''d):	LENGTH: <b>3482</b> mm	
20	TRANSIENT (X'd):	WIDTH: <b>1743</b> mm	
21	SYNCHRONOUS (Xd):	DEPTH: <b>1848</b> mm	
22	STATOR LEACKEGE REACTANCE X1 : <b>FOR MOTOR</b> <b>EQUIVALENT CIRCUIT PARAMETERS PLEASE REFER TO ATTACHMENTS</b>	DISTANCE TO REMOVE ROTOR:	mm
23	ROTOR CIRCUIT REACTANCE X2:	NET WEIGHT: <b>5100±5%</b> Kg	
24	MAGNETIZING REACTANCE XM:	SHIPPING WEIGHT:	Kg
25	STATOR CIRCUIT RESISTANCER1 :	ROTOR WEIGHT:	Kg
26	ROTOR CIRCUIT RESISTANCE R2 :	MAX. ERECTION WEIGHT:	Kg
			
27	CORE LOSSES RESISTANCE RC : ..... Ω	<b>STARTING: (Note 8)</b>	
28	<b>ROTOR RUNNING</b>	[ X ] DIRECT ON LINE [ ] REDUCED VOLTAGE	
29	RESISTANCE ..... REACTANCE:	%TAP:.....	
30	OPEN CIRCUIT TIME CONSTANT (T'do):	[ ] LOADED [ ] UNLOADED	
31	TRANSIENT SHORT CIRCUIT TIME CONSTANT (T''d):	[ ] N DESIGN [ ] NY DESIGN	
32	D.C. SHORT-CIRCUIT TIME CONSTANT (Ta):		
33	<b>EFFICIENCY, CURRENT AND POWER FACTOR AS FUNCTION OF LOAD</b>	LOCKED ROTOR POWER FACTOR: <b>~25 %</b>	
34	LOAD% <b>100 75 50</b>	<b>ALLOWABLE LOCKED ROTOR WITHSTAND TIME</b>	
35	EFFICIENCY %/PF <b>96,1/0.9 96,3/0.89 95,8/0.84</b>	<b>VOLTAGE %</b> <b>100 80</b>	
36	CURRENT A <b>150A 113A 80A</b>	COLD: <b>35s ~ 50s</b>	
37	POWER FACTOR % <b>0,90 0,89 0,84</b>	HOT: <b>18s ~ 25s</b>	




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<b>G: MOTOR FEATURES</b>	
<b>1</b>	INSULATION CLASS: <input checked="" type="checkbox"/> F      TEMPERATURE RISE AS PER: <b>(Note 20)</b> <input checked="" type="checkbox"/> CLASS B
<b>2</b>	<b>MOTOR TYPE:</b> <b>DC EXCITATION</b>
<b>3</b>	<input checked="" type="checkbox"/> SQUIRREL CAGE <input type="checkbox"/> BRUSH-LESS      kW REQUIRED:
<b>4</b>	<input type="checkbox"/> SLIP RING <input type="checkbox"/> SYNCHRONOUS      V REQUIRED:
<b>5</b>	<b>DRIVE SYSTEM:</b> <input type="checkbox"/> BY PURCHASER:
<b>6</b>	<input checked="" type="checkbox"/> DIRECTED CONNECTED <input type="checkbox"/> GEAR <input type="checkbox"/> BY MANUFACTURER:
<b>7</b>	<input type="checkbox"/> OTHERS .....      DESCRIPTIONS:
<b>8</b>	<b>BEARING: (Note 9)</b>
<b>9</b>	DRIVE END BEARING:      NON-DRIVE END BEARING:
<b>10</b>	BEARING TYPE: <b>Sleeve bearings with self-lubrication</b> <b>VARIABLE SPEED DRIVE: (Note 10)</b>
<b>11</b>	LUBRICATION: <input checked="" type="checkbox"/> OIL <b>VG 22 (ISO 3448)</b> <input type="checkbox"/> GREASE <input type="checkbox"/> FOR STARTING
<b>12</b>	LUBE OIL REQUIRED: <b>3 LITRER FOR EACH BEARING</b> <input type="checkbox"/> FOR CONTINUOUS VARIABLE SPEED
<b>13</b>	<b>BEARING TEMPERTURE INDICATORS:</b> <input type="checkbox"/> OTHERS:
<b>14</b>	<input type="checkbox"/> N.O. CONTACTS <input type="checkbox"/> N.C. CONTACTS <b>BEARING TEMPERTURE DETECTORS (Note 11)</b>
<b>15</b>	<input checked="" type="checkbox"/> SET AT <b>95°C</b> FOR ALARM <input type="checkbox"/> THERMISTORS <input checked="" type="checkbox"/> RESISTANCE TEMP. DETECTOR: <b>PT100</b>
<b>16</b>	<input checked="" type="checkbox"/> SET AT <b>100°C</b> FOR SHUTDOWN      NUMBERING PER BEARING:
<b>17</b>	<input type="checkbox"/> DESCRIPTIONS <input type="checkbox"/> RESISTANCE MATERIALS: <b>Resistance value at 0°C is 100Ω / Platinum</b>
<b>18</b>	<b>WINDING TEMPERATURE DETECTORS: (Note 11)</b>
<b>19</b>	<input type="checkbox"/> THERMISTOR: NUMBER FOR PHASE      N°      TEMPERATURE SWITCH: <input type="checkbox"/> YES <input checked="" type="checkbox"/> NO
<b>20</b>	<input checked="" type="checkbox"/> TEMPERATUER COEFFICIENT ( <b>PT100</b> ) <b>6 x RTD's Pt100 (TWO PER PHASE)</b> RESISTANCE TEMPERATURE DETECTORS: No./Phase <b>2</b>
<b>21</b>	<input type="checkbox"/> NEG. TEMPERATURE COEFFICIENT <input type="checkbox"/> RESISTANCE MATERIALS <b>Platinum</b> <input type="checkbox"/> OHM <b>100</b>
<b>22</b>	SELECTOR SWITCH AND INDICATOR BY: <input type="checkbox"/> MAX. STATOR WINDING TEMPERATURE:
<b>23</b>	<input type="checkbox"/> PURCHASER <input type="checkbox"/> MANUFACTURER      ALARM: <b>135°C</b> SHUTDOWN: <b>140°C</b>
<b>24</b>	<b>FEEDING CABLE(S):</b> <b>3C-185mm2 (1 RUN)</b>
<b>25</b>	CABLE TYPE: (CU XLPE INSULATED, ARMoured, PVC JACKETED)
<b>26</b>	<b>VIBRATION: (Note 12)</b> <b>MOTOR DIFFERENTIAL PROTECTION: (Note 13)</b> <b>NOT APPLICABLE FOR P&lt;1500KW</b>
<b>27</b>	<input checked="" type="checkbox"/> VIBRATION GRADE "A" <input type="checkbox"/> VIBRATION GRADE "B" <input type="checkbox"/> SELF BALANCED
<b>28</b>	<input type="checkbox"/> VIBRATION TRANSDUCERS: <b>N/A</b> <input type="checkbox"/> START POINT CT-METHOD
<b>29</b>	MAKE: ..... <input type="checkbox"/> CT DESCRIPTION:
<b>30</b>	<input checked="" type="checkbox"/> KEYPHASER LOCATION: <b>On Motor Shaft N/A</b>
<b>31</b>	<input checked="" type="checkbox"/> WIRING UP TO A DEDICATED JUNCTION BOX
<b>32</b>	<b>TEWAC &amp; TEIGF MOTORS</b>
<b>33</b>	COOLING WATER REQUIRED: .....      TEMPERATURE RAISE: .....
<b>34</b>	PRESSURE DROP: .....
<b>H: TERMINAL BOX &amp; COUPLING (Note 14)</b>	
<b>1</b>	<b>MAIN TERMINAL BOXES (VDE):</b> Connections possible from directions 2A, 2B, 2C and 2D
<b>2</b>	EXECUTION: <b>Ex eb IIC IP66</b>
<b>3</b>	LOCATION: <input checked="" type="checkbox"/> RIGHT <input type="checkbox"/> LEFT
<b>4</b>	CABLE ENTRY: NO. <b>1</b> HOLE(S) <b>M80</b>
<b>5</b>	THREADED:      ISO M
<b>6</b>	<b>AUX. TERMINAL BOXES (VDE):</b> <b>Two Boxes (Space heater&amp;RTDs)</b>
<b>7</b>	EXECUTION: <b>Ex eb IIC IP66</b>
<b>8</b>	LOCATION: <input checked="" type="checkbox"/> RIGHT <input type="checkbox"/> LEFT
<b>9</b>	CABLE ENTRY: <b>1xM20 (Space Heater) + 1xM32 (Windings RTDs)</b>
<b>10</b>	THREADED:      ISO <b>M20</b> <b>1xM25 bearing RTDs</b>
<b>1</b>	<b>STAR POINT TERMINL BOX (VDE)</b> <b>COUPLING:</b>
<b>2</b>	EXECUTION:      SUPPLIED BY:






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I: ACCESSORIES AND VARIOUS	
1	SPACE HEATERS:N°: POWER: <b>400 W</b> RATED VOLTAGE: [ <input checked="" type="checkbox"/> ]230 V (<3kW) [ ] 400 V (≥3kW) <b>(Note21)</b>
2	NAME PLATES LANGUAGE: <b>ENGLISH</b> Indication as per Std + Degree of Protection
3	EXTERNAL COLOUR: <b>RAL 5010 (GENTIAN BLUE)</b> TYPE: Qty PAINTING SPECIFICATION: <b>(Note 15)</b>
4	[ ] VIBRATION DETECTOR AND MONITORING <b>N/A</b> @ @
5	[ ] COOLING AIR TEMPERATURE DETECTORS @ @
6	[ ] WATER LEAKAGE DETECTOR (COOLING SYSTEM) <b>N/A</b> @ @
7	[ ] CONTROL FLOW SWITCH @ @
8	[ ] STAR POINT TERMINAL BOX @ @
9	[ ] INTERNAL AIR FILTER
10	[ ] AXIALLY-MOUNTED SPEEDOMETER DYNAMO (IF NECESSARY)
11	[ ] ACCESSORIES
12	[ ] SUN SHADES CANOPY @ @
13	[ <input checked="" type="checkbox"/> ] LIFTING EYES @ @
14	[ ] DRAIN PLUG @ @
15	[ <input checked="" type="checkbox"/> ] EARTHING BOLT @ @
16	[ ] CABLE GLANDS @ @
17	<b>AIR FILTER @</b>
18	[ ] DIFFERENTIAL PRESSURE SWITCH
19	[ ] TYPE: .....
J: SITE CONDITION (See Spec. DPC-EL-SPC-0001)	
1	INSTALLATION: [ ] INDOOR [ <input checked="" type="checkbox"/> ] OUTDOOR USE OF CANOPY REQUIRED: [ ] YES [ ] NO
2	MAX. AMBIENT TEMPERATURE: <b>+ 48°C</b> MIN. AMBIENT TEMPERATURE: <b>- 4°C</b>
3	DESIGN TEMPERATURE: <b>+ 48°C</b> EQUIPMENT EXPOSED TO SUNLIGHT: [ <input checked="" type="checkbox"/> ] <b>(Note 6)</b>
4	UNUSUAL CONDITIONS:( <b>Note 16</b> ) [ ] DUST [ ] FUMES [ <input checked="" type="checkbox"/> ] OTHERS: BAROMETRIC PRESSURE (Avg): <b>914 mbar</b>
5	HEIGH ABOVE SEA LEVEL: <b>915 m</b> MAX. HUMIDITY % AT -°C: <b>100%</b>
K: MATERIAL TYPE	
1	ROTOR CAGE BARS: INTERNAL OR EXTERNAL FANS / FAN GUARD:
2	STATOR WINDING: SHAFT:
3	TERMINAL BOXES: BEARING ELEMENTS:
4	NAME PLATE: NUT & BOLTS:
L: TESTS	
1	<b>ROUTINE TESTS: (Note 17)</b> <b>TYPE TESTS: (Note 18)</b>
2	[ <input checked="" type="checkbox"/> ] RESISTANCE CIRCUITS [ <input checked="" type="checkbox"/> ] ON LOAD TEST ACCORDING TO: IEC 60034-2
3	[ <input checked="" type="checkbox"/> ] NO LOAD TEST [ ] TYPE TEST REQUIRED BY RELEVANT
4	[ <input checked="" type="checkbox"/> ] SHORT CIRCUIT TEST STANDARD FOR HAZARDOUS MOTORS AS PER IEC
5	[ <input checked="" type="checkbox"/> ] MEASUREMENT OF VIBRATION AND SOUND LEVEL [ <input checked="" type="checkbox"/> ]TYPE TEST FOR NON HAZARDOUS MOTORS AS PER IEC STANDARDS.
6	[ ] OVER SPEED TEST HIGH-VOLTAGE TEST AND INSULATION RESISTANCE BEFORE AND AFTER [ <input checked="" type="checkbox"/> ] HEAT RUN
7	[ <input checked="" type="checkbox"/> ] WINDING INSULATION TEST [ <input checked="" type="checkbox"/> ] FULL LOAD HEAT RUN
8	[ <input checked="" type="checkbox"/> ] INSULATION RESISTANCE [ <input checked="" type="checkbox"/> ] MEASUREMENT OF SLIP AT FULL LOAD
9	[ ] FOR Ex MOTORS ROUTINE TEST REQUIRED BY RELAVANT STD. [ <input checked="" type="checkbox"/> ] MEASUREMENT TO ALLOW CALCULATION OF PULL-OUT TORQUE
10	[ <input checked="" type="checkbox"/> ] CHECKING OF PROTECTION DEGREE MEASUREMENT TO ALLOW CALCULATION OF EFFICIENCY AT FULLY, [ <input checked="" type="checkbox"/> ] THREE-QUARTER AND HALF LOAD
11	[ <input checked="" type="checkbox"/> ]MEASUREMENT OF WINDING RESISTANCE (COLD) [ <input checked="" type="checkbox"/> ] HIGH-VOLTAGE AND CONTINUITY TESTS ON BUILT-IN TEMPERATURE DETECTORS
12	[ <input checked="" type="checkbox"/> ] MEASUREMENT TO ALLOW CALCULATION OF LOCKED ROTOR <b>ADDITIONAL TESTS</b> CURRENT AND TORQUE
13	[ <input checked="" type="checkbox"/> ] HIGH-VOLTAGE TEST [ ] AIR GAP MEASURING [ <input checked="" type="checkbox"/> ] <b>VISUAL INSPECTION AND DIMENSIONAL CHECK</b>
14	[ ] ROTOR INERTIA MEASURING [ <input checked="" type="checkbox"/> ] <b>REVIEW OF TEST CERTIFICATE</b>

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M:	NOTES
<b>1</b>	VENDOR SHALL FILL IN THE PRESENT DATA SHEET FORM SEPARATELY FOR EACH MOTOR.
<b>2</b>	AS PER IEC 60034-7 "CLASSIFICATION OF TYPES OF CONSTRUCTION AND MOUNTING ARRANGEMENT (IM CODE)".
<b>3</b>	AS PER SELECTION OF EQUIPMENT FOR CLASSIFIED HAZARDOUS AND UNCLASSIFIED AREAS SPECIFICATION DPC-EL-SPC-0004.ALSO MECHANICAL PROTECTION DEGREE ACCORDONG TO IEC 60034-5 & IEC 60529.
<b>4</b>	STARTING CURRENT TO RATED CURRENT RATIO SHALL NOT EXCEED THE FOLLOWING VALUES: - MOTORS RATED POWER LESS THAN 2.000 KW: 5,5 IN - MOTORS RATED POWER HIGHER THAN OR EQUAL TO 2.000 KW: 4,0 IN
<b>5</b>	SERVICE FACTOR GREATER THAN 1.0 ARE PERMITTED ONLY WHEN SPECIFIED IN THE DATA SHEET.
<b>6</b>	OUTDOOR LOCATIONS ELECTRICAL EQUIPMENT SHALL BE SUITABLE FOR THE ENVIRONMENTAL CONDITIONS (E.G. DUST, MOISTURE, SNOW OR RAIN) WITH ADDITIONAL PROTECTION PROVIDED (E.G. RAIN SHIELDS, SUN SHIELDS) WHERE REQUIRED.
<b>7</b>	SUPPLIER OF ALL EQUIPMENT SHALL BE INCLUDED.
<b>8</b>	STARTING PERFORMANCE OF SINGLE-SPEED THREE-PHASE CAGE INDUCTIONS MOTORS ACCORDING TO IEC 60034-12. MOTORS SHALL BE SUITABLE TO START AND ACCELERATE THE LOAD AT 80% OF RATED VOLTAGE AT ITS TERMINALS AND CAPABLE TO WITHSTANDING ANY TRANSIENT TORQUE DUE TO THE POWER NETWORK.
<b>9</b>	BEARING SHALL BE IN COMPLIANCE WITH THE REQUIREMENTS OF ISO 281. MOTORS FOR VERTICAL PUMPS, INCLUDING IN LINE SHALL HAVE RAIN PROTECTION COVER.ALSO VERTICAL MOTORS SHALL HAVE THRUST BEARINGS SUITABLE FOR THE LOAD IMPOSED BY THE DRIVEN MACHINERY; HOUSING OF SLEEVE BEARING SHALL BE EQUIPPED WITH SIGHT-FEED OILER OR SIGHT GAUGE MARKED WITH PROPER OIL LEVEL.
<b>10</b>	IN CASE OF MOTOR WITH VARIABLE SPEED DRIVE (VSD), VENDOR SHALL FILL IN ALSO VSD DAT SHEET.ONLY FOR VARIABLE SPEED MOTORS. IF SYNCHRONOUS MOTORS HAVE TO BE STARTED VIA STARTING CONVERTER (DEPENDING ON THE NETWORK CONDITIONS) THE MOTOR DESIGN SHALL BE ACCORDINGLY AND SHALL BE EXECUTED IN CLOSE COORDINATION WITH THE VSD (VARIABLE SPEED DRIVES) SYSTEM DESIGN.
<b>11</b>	RTDs SHALL BE PROVIDED FOR MV MOTORS ( $\geq 150\text{kW}$ ) AND WHERE REQUIRED BY MACHINE MONITORING SYSTEM. A MINIMUM OF THREE (ONE PER PHASE) DETECTORS SHALL BE PROVIDED BETWEEN THE COIL SIDES TO MEASURE THE WINDING TEMPERATURE AND THREE (ONE PER PHASE) AT THE BASE OF THE SLOTS TO MEASURE CORE TEMPERATURE, EACH PLACED $120^\circ$ APART. SLEEVE BEARINGS FOR MV-MOTORS SHALL BE EQUIPPED WITH A DOUBLE RESISTANCE TEMPERATURE DETECTOR OF THE PT 100, 3 OR 4 WIRE TYPE.
<b>12</b>	LIMITS OF MAXIMUM MECHANICAL VIBRATION MAGNITUDE ACCORDING TO IEC 60034-14.
<b>13</b>	DIFFERENTIAL PROTECTION SHALL BE PROVIDED ONLY FOR MOTOR LARGER THAN 1500 kW. MOTORS SHALL INCLUDE THE SIX CURRENT TRANSFORMERS FOR DIFFERENTIAL PROTECTION (THREE CT'S INSIDE THE STAR POINT TERMINAL BOX AND THREE CT'S FOR THE INSTALLATION IN THE FEEDING UNIT).THE ENCLOSURE TYPE OF THE TERMINAL BOX SHALL NOT BE LOWER THAN THE MAIN MOTOR ENCLOSURE.
<b>14</b>	1- THE BOX SHALL BE OVERSIZED AND COMPATIBLE WITH THE DIMENSIONS OF POWER CABLES AND RELEVANT ACCESSORIES (LUGS AND TERMINATIONS), SO LOCATED AS TO ENSURE AN EASY SET-UP OF CABLE ENDS AND ACCESS TO TERMINALS. 2- THERE SHALL BE SEPARATE TERMINAL BOXES FOR MAINS, SPACE HEATER AND MEASURING SENSORS FOR TEMPERATURE OF BEARINGS AND VIBRATIONS. SEPARATED BOXES LOCATED ON THE OPPOSITE SIDE OF THE MAIN ONE. 3- ALL INLET HOLES SHALL BE PROVIDED WITH THREADED PLUGS SUITABLE FOR THE TYPE OF PROTECTION OF THE TERMINAL BOXES. 4-MAIN BOX FOR 6 KV MOTORS WILL BE ALSO CAPABLE TO ACCOMMODATE THE SURGE ARRESTERS. 5-GASKETS SHALL BE LOCATED IN SUITABLE SEATS AND SHALL BE OF MATERIALS WITH AGE-RESISTING CHARACTERISTICS AND ELASTIC PROPERTIES PRACTICALLY UNAFFECTED BY TEMPERATURE VARIATIONS OCCURRING DURING MOTOR RUNNING. 6-FOR MOTOR RATED POWER EQUAL TO OR HIGHER THAN 3.5 KW, A STAR POINT TERMINAL BOX SHALL BE INCLUDED

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15	AS PER PAINTING SPECIFICATION DPIC9812-000-000-PI-JSD-2300-0001.
16	DUST OVER THE FLAT TERRAIN AND A HIGH CORROSION IN THIS AREA MUST BE CONSIDERED. THE PRESENCE OF CORROSIVE GAS MIXTURES AND POLLUTED RAINFALL MUST BE CONSIDERED. MOTORS CAN BE DIRECTLY EXPOSED TO SUNLIGHT AND TO WEATHER INJURY, WITHOUT ANY ADDITIONAL PROTECTION.
17	FOR FURTHER DETAILS REGARDING ROUTINE TESTS AND FOR WITNESS TESTS REFER TO RELATED SPECIFICATION.
18	TYPE TEST SHALL BE QUOTED SEPARATELY IN THE BID.
19	THE SUPPLY SHALL BE IN COMPLIANCE WITH JOB SPECIFICATION FOR SUPPLY MEDIUM VOLTAGE MOTORS DPC-EL-SPC-0020.
20	WINDING INSULATION PHASE TO PHASE AND PHASE TO EARTH, SHALL BE CLASS F NON HYGROSCOPIC WITH A 85 °K TEMPERATURE RISE MEASURED BY SLOT-EMBEDDED RESISTANCE TEMPERATURE DETECTOR ( RTD ) AND 80 °K AVERAGE TEMPERATURE RISE ( ACCORDING TO IEC 60034 ) OVER 40 °C AMBIENT MAXIMUM AT RATED OUTPUT ( 1.0 SERVICE FACTOR RATING ).
21	LEAD OF SPACE HEATERS, CONTROL OR DETECTION SIGNAL SHALL BE TERMINATED IN TERMINAL BOXES SEPARATE FROM THAT HAVE BEEN USED FOR THE MAIN POWER LOAD TERMINAL BOXES. SPACE HEATERS SHALL BE PROVIDED FOR MOTORS ABOVE 150KW.
22	THE MOTOR TORQUES DURING STARTING (LOCKED-ROTOR TORQUE, PULL-UP TORQUE, BREAKDOWN TORQUE), AT RATED FREQUENCY AND AT MINIMUM VOLTAGE ALLOWED, SHALL ENSURE A CORRECT STARTING, ACCORDING TO IEC 60034 UNLESS LOAD TORQUE REQUIRES MOTOR WITH SPECIAL CHARACTERISTICS.
23	VENDOR SHALL SUPPLY THE REQUIRED ELECTRICAL CERTIFICATIONS AND DOCUMENTS AS PER SPECIFICATION (DPC-EL-SPC-0020).
24	MANUFACTURER SHALL ALSO QUOTE SEPARATELY, SUPERVISION ON SITE FOR COMMISSIONING AND START UP OF THE MOTOR
25	INFORMATION TO BE COMPLETED BY MANUFACTURER INFORMATION TO BE COMMUNICATED OR CONFIRMED LATER

**Note:**

**Motor need to be prepurging before start:**

**Prepurging volume: 37.5 m<sup>3</sup> for minimum 15 minute (flow rate minimum 150 m<sup>3</sup>/h)**

## Three-phase induction motor with squirrel cage rotor Drehstromasynchronmotor mit Kurzschlußläufer

### Electrical data / Elektrische Daten

Rated motor power / Bemessungsleistung	kW	1340		
Rated motor voltage / Bemessungsspannung	V	Y	6000	
Rated voltage tolerance / Bemessungsspannungsbereich	Zone A (V: ±5%; f: ±2%)			
Rated frequency / Bemessungsfrequenz	Hz	50		
Number of poles / Polzahl	2			
Rated motor speed / Bemessungsdrehzahl	rpm	2984		
Rated motor current / Bemessungsstrom	A	150		
Power factor / Leistungsfaktor (at / bei 100% - 75% - 50%)		0,90	0,89	0,84
Efficiency / Wirkungsgrad (at / bei 100% - 75% - 50%)		96,1%	96,3%	95,8%
Breakdown-/Rated torque / Kipp-/Bemessungsmoment (Tb/Tn)	2,5			
Starting-/Rated torque / Anzugs-/Bemessungsmoment (Ts/Tn)	0,6			
Starting-/Rated current / Anzugs-/Bemessungsstrom (Is/In)	5,5			

### Mechanical data / Mechanische Daten

Weight / Gewicht	kg	5100±5%		
Rotor inertia / Rotorträgheitsmoment	kgm <sup>2</sup>	16,0		
Direction of rotation (from DE side) / Drehrichtung (von A-Seite)	clockwise / rechts			
Balance / Wuchtart	Half-key / Halbkeil			
Vibration grade / Schwinggrößenstufe	A			
Bearing / Lagerart	Sleeve bearings with self lubrication			
Bearing type DE / Lagertyp AS	EM-ZLB 09S100 12-100 10-100			
Oil content DE / Öl-Inhalt AS	l	3		
Bearing type NDE / Lagertyp BS	EMkZLB 09S100 12-100 10-100			
Oil content NDE / Öl-Inhalt BS	l	3		
Lubricating oil / Schmieröl	DIN 51517-CL/CLP / VG 22 (ISO 3448)			

### General data / Allgemeine Daten

Frame size / Baugröße	450			
Type of construction / Bauform	IM B3			
Material of housing / Gehäusematerial	Welded steel / Stahl geschweißt			
Material of terminal box / Klemmenkastenmaterial	Welded steel / Stahl geschweißt			
Degree of protection / Schutzart	IP55			
Method of cooling / Kühlart	IC611			
Thermal class - temperature rise / Wärmeklasse - Erwärmung	F/B			
Duty type / Betriebsart	S1			
Sound pressure level, no load at 1 m / Schalldruckpegel, Leerlauf bei 1 m	dB(A)	78+3		
Painting / Anstrich	RAL 5010			
Standards / Normen	EN 60034-1; EN 60079-0; EN 60079-7			
Ex-Protection / Ex-Schutz	Ex ec IIC T3 Gc			

### Site conditions / Aufstellbedingungen

Ambient temperature / Umgebungstemperatur (min / max)	°C	-5	+50
Max. altitude above sea level / Max. Höhe über NHN	m	1000	

### Accessories / Zubehör

Thermal protection / Temperaturüberwachung	6 + 2 x PT100 / PT100			
Space heater / Stillstandsheizung	V	220-240	W	?
Space heater bearings / Stillstandsheizung Lager	V		W	?

The rating plate values may vary from the calculated values. / Abweichungen zwischen berechneten und Leistungsschilddaten sind möglich.

Type	Identification	Prepared	Date	Checked	Revision	Status	Sheet
NDKK450-02-S	11000101138-39	Gae	25.04.22	PR	00	C	1/2

**Accessories / Zubehör**

Winding: 6 x RTD's Pt100 ohms at 0°C, 2 to 4-wire, with transmitters (2/phase)  
Bearings: 2 x double RTD's Pt100 ohms at 0°C, 2 to 4-wire, with transmitters (1/bearing)  
Space heater: 220-240V, 1ph , a.c.  
Number of consecutive starts cold/hot: 3/2  
Starting method: DOL  
Application: screw compressor

Type	Identification	Prepared	Date	Checked	Revision	Status	Sheet
NDKK450-02-S	11000101138-39	Gae	25.04.22	PR	00	C	2/2

## Three-Phase-Induction Motor with Squirrel Cage Rotor

### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7

### Calculated Start-Up Data

Motor voltage	$U/U_N$	1.00	0.80		
Locked-rotor torque	$M_A/M_N$	0.60	0.37		
Pull-up torque	$M_S/M_N$	0.59	0.37		
Breakdown torque	$M_K/M_N$	2.50	1.58		
Locked-rotor current	$I_A/I_N$	5.50	4.27		

### Calculated Partial Load Data


$P/P_N$	1.25	1.00	0.75	0.50	
$\cos \varphi$	0.89	0.90	0.89	0.84	
$\eta$ [%]	95.7	96.1	96.3	95.8	

### Additional Technical Ratings and Information

Rotor material: E-CU

Measuring surface sound pressure level (no-load): 78 dB(A), tol.: 3 dB(A)

The mains voltage may vary by up to +-5% and the mains frequency by up to +-2% from the rated values, in keeping with zone A according to IEC 60034-1

	Document type	Created		
	Electrical Data Sheet	Gae		
	Title	Approved by		
	Type : NDKK450-02-G	Pr		
	Order No. : 11000101138-39	Rev.	Date of issue	Sheet
			2022-03-21	1/7

## Three-Phase-Induction Motor with Squirrel Cage Rotor

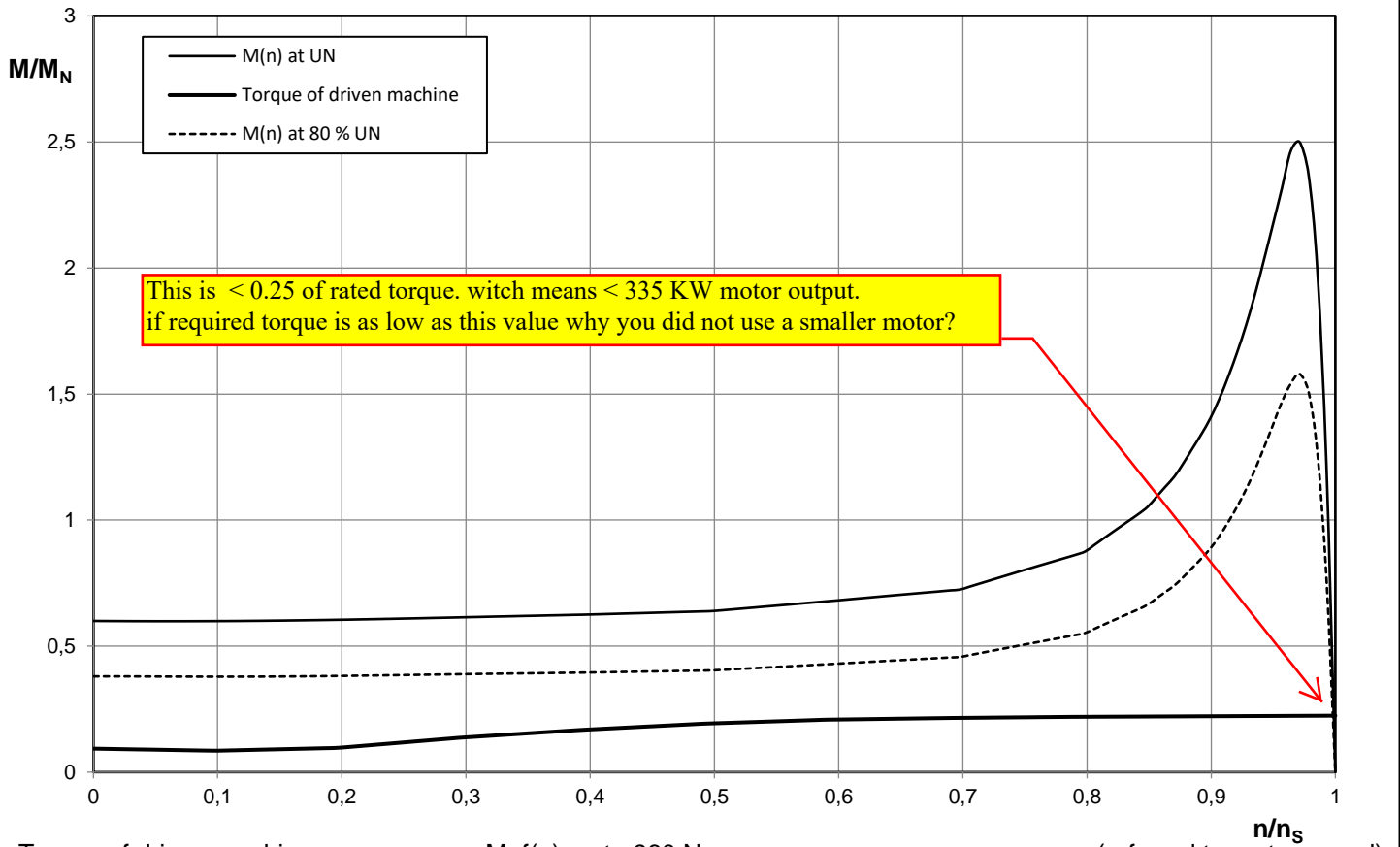
### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7



Torque of driven machine	$M=f(n)$ up to 960 Nm	(referred to motor speed)
Driven machine	Srew compressor	
Required power		
Moment of inertia (load)	3.1 kgm <sup>2</sup>	(referred to motor speed)
Starting time	3 s	at $U/U_N = 1.00$
	6 s	at $U/U_N = 0.80$
Perm. number of starts	3 cold, 2 warm	at $U/U_N = 1.00$
	3 cold, 2 warm	at $U/U_N = 0.80$
		1000 per year

	Document type	Created		
	Starting Data $M=f(n)$	Gae		
	Title	Approved by		
	Type : NDKK450-02-G	Pr		
	Order No. : 11000101138-39	Rev.	Date of issue	Sheet
			2022-03-21	2/7

## Three-Phase-Induction Motor with Squirrel Cage Rotor

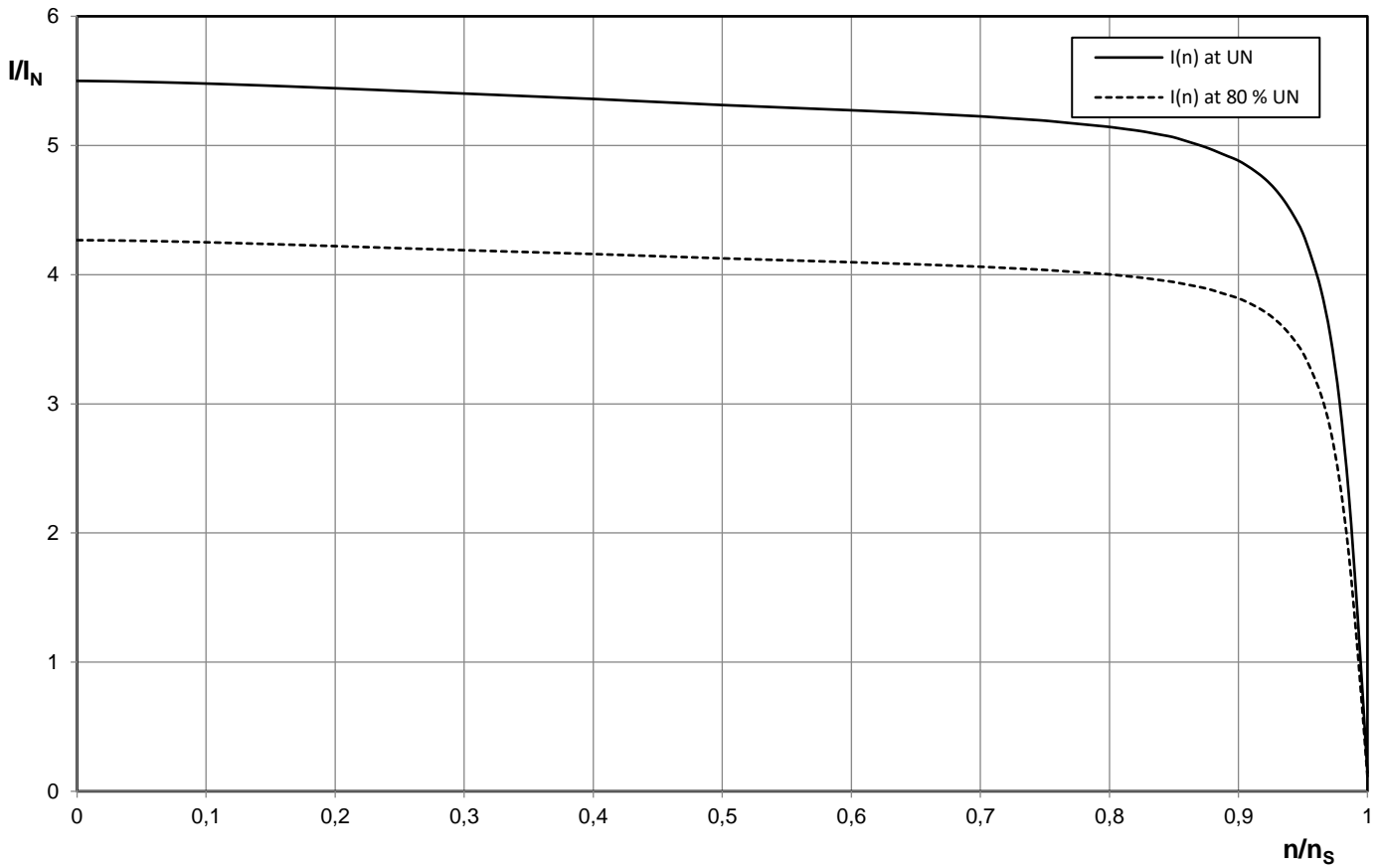
### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7



Document type

Starting Data  $I=f(n)$

Title

Type : NDKK450-02-G

Order No. : 11000101138-39

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Gae

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2022-03-21

Sheet

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## Three-Phase-Induction Motor with Squirrel Cage Rotor

### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

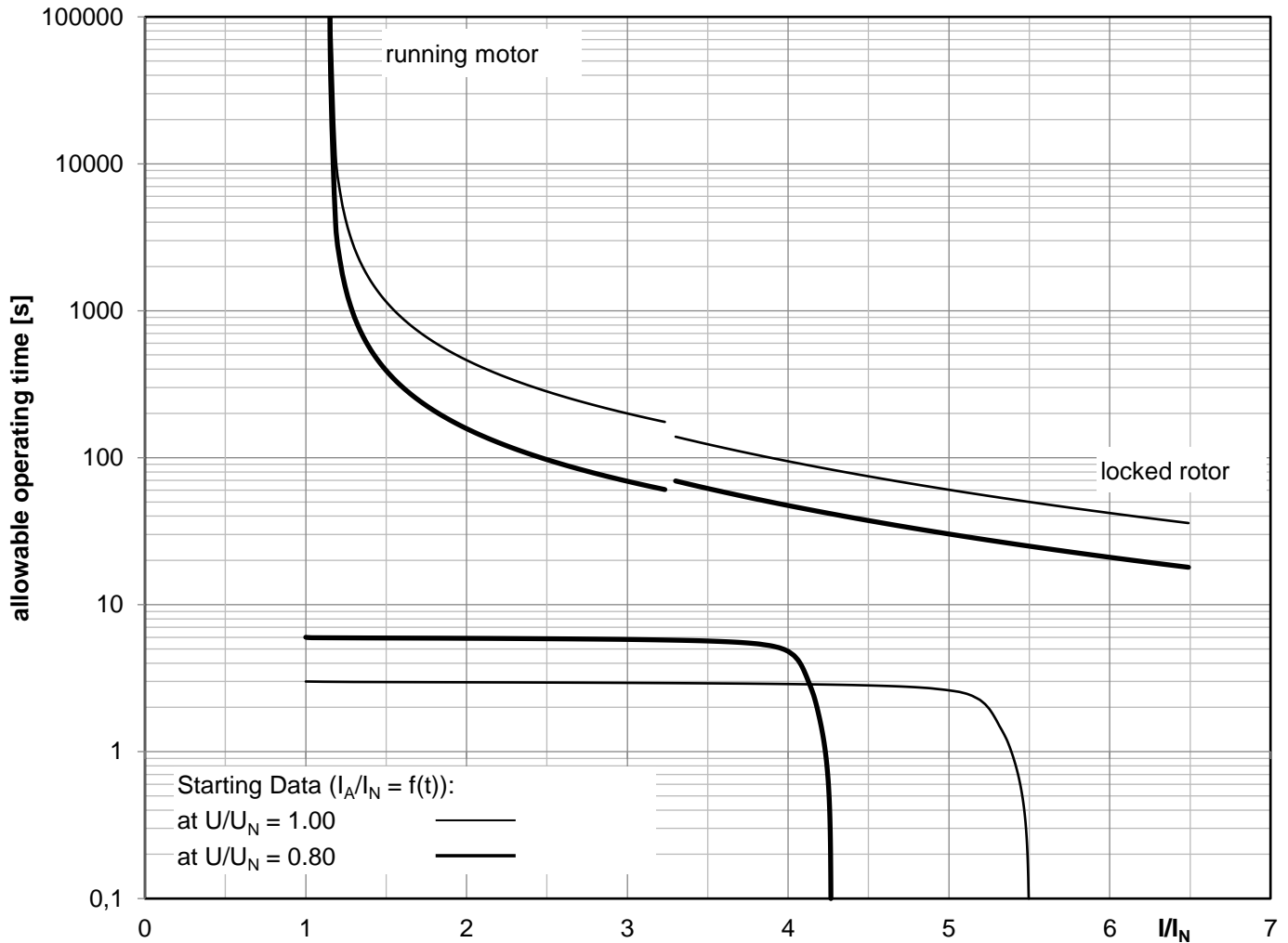
Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7

— for cold motor condition

— for warm motor condition



Thermal copper time constant (short-term load variation)	12 min
Thermal time constant (long-term load variation)	25 min
Thermal time constant for cooling down (standstill)	176 min

	Document type	Created		
	Title	Approved by		
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## Three-Phase-Induction Motor with Squirrel Cage Rotor

### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7

$\text{Trans. Torque in Air Gap: } M(t)/M_N = \Sigma (M/M_N \times e^{(t*\tau)} \times \sin(2\pi \times f \times t + \varphi))$
---

#### Starting with locked rotor and $U_{Line} = 100 \%$

$M/M_N$	$\tau/s^{-1}$	f/Hz	$\varphi/degree$
0.51	0.00	0.00	90.00
0.51	-39.35	0.00	90.00
4.14	-0.26	50.00	-172.95
4.14	-39.09	50.00	-7.05

$$M_{max}/M_N = 4.48 \text{ at } t = 134.6\text{ms}$$

#### 3-pole terminal short circuit

$M/M_N$	$\tau/s^{-1}$	f/Hz	$\varphi/degree$
-0.53	-24.17	0.00	90.00
-0.22	-54.53	0.00	90.00
5.98	-39.35	48.90	162.89


$$M_{max}/M_N = 5.37 \text{ at } t = 5.6\text{ms}$$

#### 2-pole terminal short circuit

$M/M_N$	$\tau/s^{-1}$	f/Hz	$\varphi/degree$
0.19	0.00	0.00	90.00
-0.53	-24.17	0.00	90.00
-0.06	-54.53	0.00	90.00
2.87	-12.09	49.84	175.15
1.48	-27.27	0.93	15.36
3.00	-39.35	48.90	162.64
1.44	0.00	100.00	-5.24
0.39	-12.09	50.16	91.15
1.49	-27.27	99.07	-15.16

$$M_{max}/M_N = 6.93 \text{ at } t = 7\text{ms}$$

The value of the mechanical torque of the whole shafting can only be determined by using the above transient torques in a torsional analysis calculation. The plant manufacturer is responsible for the torsional vibrations analysis.

	Document type	Transient Torques		Created	Gae	
	Title			Approved by	Pr	
	Type :	NDKK450-02-G		Rev.	Date of issue	Sheet
	Order No. :	11000101138-39			2022-03-21	5/7

## Three-Phase-Induction Motor with Squirrel Cage Rotor

### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7

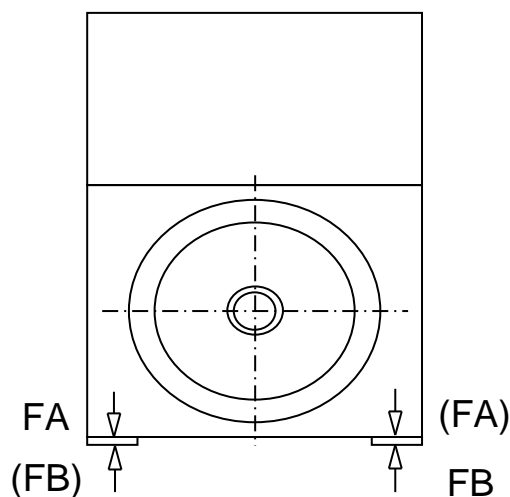
### Foundation Load

The listed foundation loads are derived from a stress analysis for a rigid foundation, caused by the maximum dynamic torque and the machine weight. The forces occur alternately on each side of the machine, irrespective of the direction of rotation.

Transfer of vibrations from the surrounding has to be avoided by appropriate layout of foundation. On the basis of DIN 4024 Part 1 the natural frequencies  $f_n$  of the system - machine on foundation - must differ as follows from the operating frequencies  $f_m$  (for mains-fed operation: Rotating frequency, double rotating frequency, line frequency and double line frequency, for converter-fed operation: Rotating frequency, double rotating frequency, supply frequency and double supply frequency):

- 1. Natural frequency of system:  $f_1 \geq 1.25 f_m$  or  $f_1 \leq 0.8 f_m$
- Higher natural frequencies:  $f_n \geq 1.1 f_m$  or  $f_n \leq 0.9 f_m$

→ The plant manufacturer is responsible for the design of the foundations!



#### 2-pole terminal short circuit

compressive force  $FA = 60 \text{ kN}$   
tensile force  $FB = 8 \text{ kN}$

(forces on one side of the machine)

	Document type	Created		
	Foundation Load	Gae		
	Title	Approved by		
	Type : NDKK450-02-G	Pr		
	Order No. : 11000101138-39	Rev.	Date of issue	Sheet
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## Three-Phase-Induction Motor with Squirrel Cage Rotor

### Operating and Installation Data

Rated-power	$P_N$	1340 kW	Connection	Y
-voltage	$U_N$	6000 V	Class of rating	S1
-frequency	$f_N$	50 Hz	Absolute altitude	<1000 m ab.s.l.
-current	$I_N$	150 A	Coolant temperature	50 °C
-speed	$n_N$	2984 1/min	Therm. class (design/util.)	155 (F) / 130 (B)
-torque	$M_N$	4289 Nm		
Power factor	$\cos\varphi$	0.9		

Standard: IEC/EN 60034-1

Tolerances: IEC/EN 60034-1

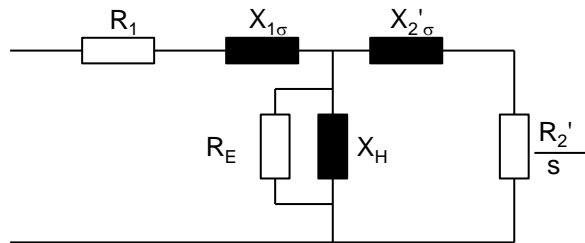
Type of ignition protection: Ex ec IIC T3 Gc, IEC/EN 60079-0,-7

### Resistances, Reactances (Calculated Values per Phase)

Values (p.u.) referred to $Z_N$	$Z_N = U_{PH} / I_{PH}$		23.1 $\Omega$
at slip		$s = 0.0053$	$s = 1$
Stator-resistance	$R_1 / Z_N$	0.00713	0.00713
Stator-leakage reactance	$X_{1\sigma} / Z_N$	0.20684	0.12954
Rotor-resistance	$R_2' / Z_N$	0.00529	0.01613
Rotor-leakage reactance	$X_{2\sigma}' / Z_N$	0.07390	0.05946
Magnetizing-reactance	$X_H / Z_N$	5.688	5.956
Ironloss-resistance	$R_E / Z_N$	186.40	186.40

The resistances apply to the warm machine.

The rotor-resistances / -reactances refer to the stator.



Document type

Equivalent-Circuit Diagram

Title

Type : NDKK450-02-G

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# Technical data for configuration

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## 1 Legend for machine dimension drawing

Position	Designation
COG	Center of gravity
DR	Direction of rotation
LA	Air discharge
LB	Attachment eye (self aligning)
LE	Air intake
ML	Maintain minimum clearance air intake and/or air outlet
WA	DE shaft end
XA	Undercut DE
⊥	Ground connection

Position	Designation
1	Terminal box stator line connection
3	Terminal box auxiliary circuits
5	Terminal box anti-condensation heating
10	Sleeve bearings DE
11	Sleeve bearings NDE
14	Air intake sound absorber
21	Connection for purge air intake
22	Connection, purge air outlet

	Document type	Created by		
	Technical data for configuration		GAE	
	Title	Approved by		
	Type : NDKK450-02-G	PR		
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## 2 Technical data

### 2.1 Mechanical data

Type of construction	IM B3 / IM 1001
Total weight	See dimension drawing
Weight of the cooler housing	0.67 t
Rotor weight	See Shaft dimension drawing
Rotor balancing	Dynamically balanced with half a feather key, without coupling half

### 2.2 Ambient conditions

Degree of protection	IP55
Cooling method	IC611
Ambient temperature	-5 ... 50 °C

### 2.3 Vibration behavior

The values are valid for measurements taken in the manufacturer's test field.  
These are valid for rated speed.

Without coupling half

Converter-fed motors are tested as standard the same as line motors.

### Bearing housing vibration

Vibration severity grade	A (DIN EN IEC 60034-14:2019)
Vibration velocity (rms value)	2.3 / 2.8* mm s <sup>-1</sup>

\* See also DIN EN IEC 60034-14:2019, Section 8.2

### 2.4 Shaft end

#### DE shaft end


Dimension drawing position	WA
Centering bore	DR M24×50 - DIN 332

#### Undercut

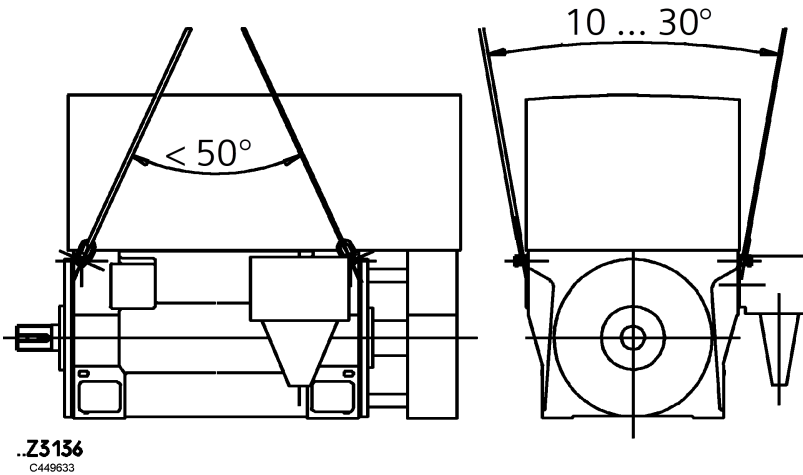
Dimension drawing position	XA
Design	E2.5×0.4 - DIN 509

### 2.5 Paint finish

Standard paint finish	
Color	RAL 5010
Total paint coat thickness	100 µm

	Document type Technical data for configuration	Created by GAE		
	Title	Approved by PR		
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## 2.6 Lifting and transporting



**.Z3136**  
C449633

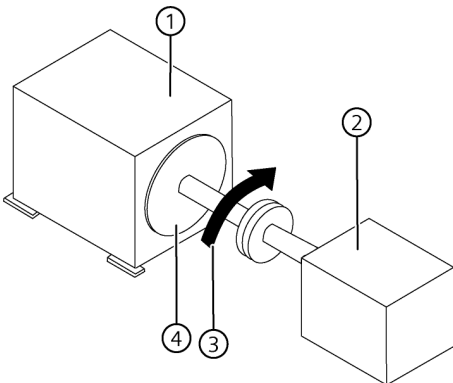
Lifting the machine, attachment points

The following applies when lifting:

Velocity  $v < 20 \text{ m min}^{-1}$ ; Acceleration  $a < 0.4 \cdot g$

The attachment points at the machine are only designed to lift the weight of the machine itself. Do not lift the machine together with base frames, adapter or sole plates.

## 2.7 Direction of rotation



- ① Motor
- ② Driven machine
- ③ Direction of rotation
- ④ DE

Dimension drawing position

DR

Direction of rotation

only clockwise rotation viewed at the DE

### Connection, clockwise rotation

Line phases in their associated phase sequence	L1	L2	L3
at the machine terminals	U	V	W

	Document type Technical data for configuration	Created by GAE	
	Title	Approved by PR	
Type : NDKK450-02-G Serial-No. : 11000101138-39	Rev.	Date of issue 2022-04-07	Sheet 5/23

## 2.8 Prepurgig

see the Operating Instructions

Overpressure Housing	Max. 50 mbar
Flow rate	Min. 150 m <sup>3</sup> h <sup>-1</sup>
Prepurging volumes	37.5 m <sup>3</sup>
Prepurging time	Min. 15 min

The final operational values are stamped on the purging plate attached to the machine. The purge plate is only created after measurement.

## 2.9 Bearing DE

### Sleeve bearings

Dimension drawing position	10
Type	EM-ZLB 09S100 12-100 10-100
Manufacturer	RENK
Lubricating oil	DIN 51517-CL/CLP
Viscosity class	VG 22 (ISO 3448)
Scope of delivery	Without oil
Changing the oil	Only with the shaft stationary

### Oil ring lubrication

Oil quantity	3 L
--------------	-----

Additional details are provided in the associated Operating and Maintenance Instructions.

## 2.10 Bearing NDE


### Sleeve bearings

Dimension drawing position	11
Type	EMkZLB 09S100 12-100 10-100
Manufacturer	RENK
Lubricating oil	DIN 51517-CL/CLP
Viscosity class	VG 22 (ISO 3448)
Scope of delivery	Without oil
Changing the oil	Only with the shaft stationary


### Oil ring lubrication

Oil quantity	3 L
--------------	-----

Additional details are provided in the associated Operating and Maintenance Instructions.

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The bearing is installed so that it is insulated.  
During operation, it is not permissible that the insulation is jumpered.

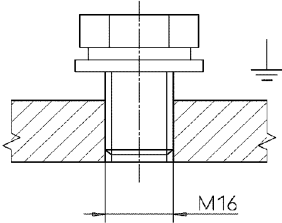
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### 3 Electrical connection

#### 3.1 Machine grounding

##### Ground connection

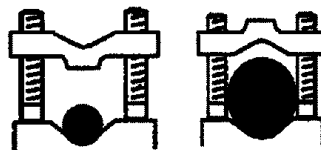
Dimension drawing position	⊥	
Conductor connection	Cable lug according to standard	
	DIN 46234	DIN 46235
Conductor cross-section max.	240 mm <sup>2</sup>	400 mm <sup>2</sup>



#### 3.2 Stator

##### Main terminal box

Dimension drawing position	1
Material	Steel
Degree of protection	IP66
Type of protection	Ex eb
Ground connection	185 mm <sup>2</sup>
Outer cable diameter	35 ... 75 mm
Cable seal	Sealing ring that can be cut
Conductor connection	Terminal clamp
Conductor cross-section	Max. 50...300 / 120...400 mm <sup>2</sup>



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### 3.3 Auxiliary circuits


#### Auxiliary terminal box

Dimension drawing position	3
Material	Stainless steel 1.4301
Degree of protection	IP66
Type of protection	Ex eb
Conductor cross-section	Max. 4 mm <sup>2</sup>
Connecting terminals	Intrinsically safe for circuits Ex i
Cable entry	Plate, removable, undrilled Customers are responsible for selecting the cable glands and machining the threaded bores.

### 3.4 Anti-condensation heating

#### Auxiliary terminal box

Dimension drawing position	5
Material	Stainless steel 1.4301
Degree of protection	IP66
Type of protection	Ex eb
Conductor cross-section	Max. 4 mm <sup>2</sup>
Cable entry	Plate, removable, undrilled Customers are responsible for selecting the cable glands and machining the threaded bores.

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## 4 Auxiliary units

### 4.1 Heating

#### Anti-condensation heating electrical machine

Voltage	220 ... 240 V
Heating power	364 ... 433 W
Ambient temperature $\vartheta_a$	-5 ...+50°C
Surface temperature $\vartheta_{B \max}$	175 °C
Type of protection	II 2G Ex eb IIC T3 Gb
Certificate	EPS 18 ATEX 1145U IECEX EPS 18.0068U



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## 5 Monitoring

### 5.1 Bearing temperature

#### Resistance thermometer

Type	2 × Pt100 / B (IEC 60751)
Number at DE	1
Number at NDE	1
Type of protection	Ex eb

### 5.2 Slot temperature

#### Resistance thermometer

Type	1 × Pt100 / B (IEC 60751)
Number	6
Type of protection	Ex eb

Assignment, thermometer to the monitored phase

Phase	Connecting terminals
U	20:1R1
V	20:2R1
W	20:3R1
U	20:4R1
V	20:5R1
W	20:6R1


Only temperature sensors integrated in the winding are suitable to monitor the winding temperature. Temperature sensors located at a different position supply incorrect values.

### 5.3 Measured value conversion

#### Measuring transducer

Number 5

Set the measuring transducer to the measuring range. Additional details are provided in the associated Operating and Maintenance Instructions.

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## 6 Monitoring setpoints

### 6.1 Slot temperature

First setting before commissioning	Shutdown	$\vartheta_0 = 120\text{ °C}$
Setting in operation	Alarm	$\vartheta_1 = \vartheta + 10\text{ K}$ ; max. 135 °C
	Shutdown	$\vartheta_2 = \vartheta + 15\text{ K}$ ; max. 140 °C

$\vartheta$  = temperature in the steady-state condition / °C

### 6.2 Bearing temperature

First setting before commissioning	Shutdown	$\vartheta_0 = 95\text{ °C}$
Setting in operation	Alarm	$\vartheta_1 = \vartheta + 2\text{ K}$ ; max. 97 °C
	Shutdown	$\vartheta_2 = \vartheta + 5\text{ K}$ ; max. 100 °C

$\vartheta$  = temperature in the steady-state condition / °C


### 6.3 Bearing housing vibration

Comply with the specifications laid down in standard DIN ISO 10816-3.

Setting values according to DIN ISO 10816-3.

Subassembly (foundation)		Rigid	Flexible
First setting before commissioning	Alarm	4.5 mm s <sup>-1</sup>	7.1 mm s <sup>-1</sup>
	Shutdown	7.1 mm s <sup>-1</sup>	11 mm s <sup>-1</sup>
Setting in operation	Alarm	$v \times 1.25$	$v \times 1.25$
	Shutdown	7.1 mm s <sup>-1</sup>	11 mm s <sup>-1</sup>

$v$  = measured basis value of the vibration velocity

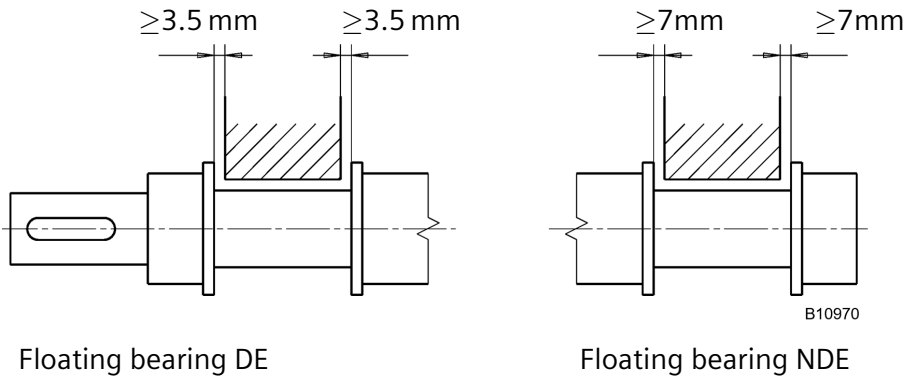
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## 7 Assembly

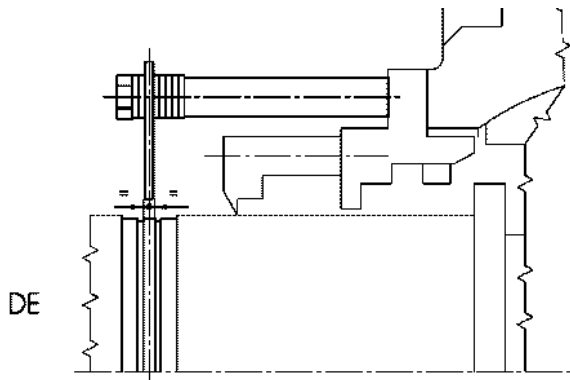
### 7.1 Axial bearing clearance

The bearings are floating bearings. The rotor must be axially guided using a locating bearing in the driven machine (driven load) or in the gearbox via the coupling.

Only use a coupling with fixed axial clearance. ( $\pm 0.5$  mm up to  $\pm 1.0$  mm).



### 7.2 Pointer for the magnetic center of the axial rotor position



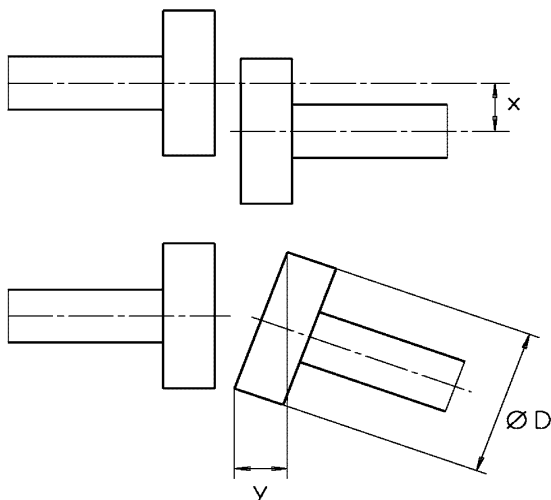
Before attaching the coupling, set the rotor to its magnetic center.

The axial bearing clearance has been correctly set if the pointer is located centered above the marking on the shaft. As a result of production tolerances, the bearing clearance can be somewhat higher than the specified values.

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### 7.3 Alignment accuracy, coupling

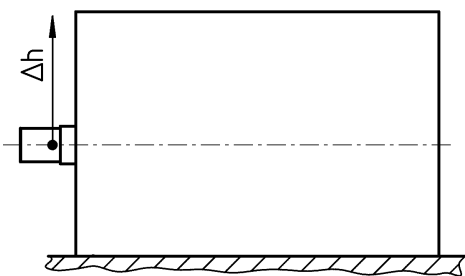
Also comply with the coupling manufacturer's instructions.



$n$	0 ... 900 min <sup>-1</sup>
$x$	Max. 0.09 mm
$y$	Max. 0.09 mm / 100 mm $\varnothing D$
$n$	900 ... 1800 min <sup>-1</sup>
$x$	Max. 0.06 mm
$y$	Max. 0.05 mm / 100 mm $\varnothing D$
$n$	1800 ... 3600 min <sup>-1</sup>
$x$	Max. 0.03 mm
$y$	Max. 0.025 mm / 100 mm $\varnothing D$


### 7.4 Thermal expansion

Shift of the non-coupled shaft end when operated with high thermal utilization levels:



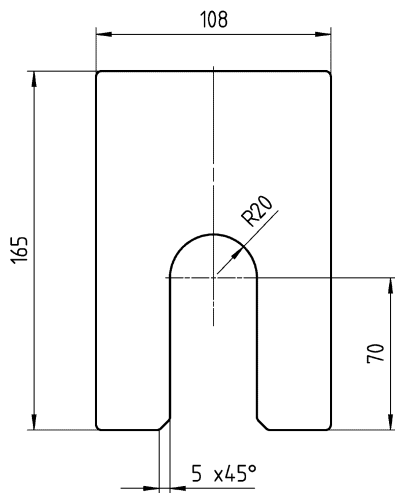
$$\Delta h = 0.17 \text{ mm}$$

To calculate the relative shifts of the machine referred to the environment, temperature expansion coefficient  $\alpha = 12 \cdot 10^{-6} \text{ K}^{-1}$  applies.

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## 7.5 Fastening

Shim geometry Material Steel / Brass



Mounting parts for fastening the machine onto a steel foundation.

(Not included in the scope of delivery)

Tightening torque for fastening screws  $M_A = 1080 \text{ Nm} \pm 15 \%$


Designation	Number	Standard	Specification
Mounting screw	4	ISO 4017	M36×140 - 8.8
Washer	4	ISO 7091	36 - 100HV
Jack screw	4	ISO 4017	M24×100 - 8.8

## 7.6 Connection for purge air intake

Dimension drawing position 21

### Air intake

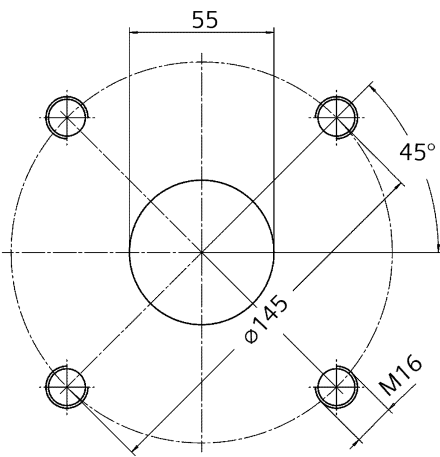
Female thread  $2 \times \text{Rp } 1/2'' + 1 \times \text{Rp } 1''$


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## 7.7 Purge air outlet

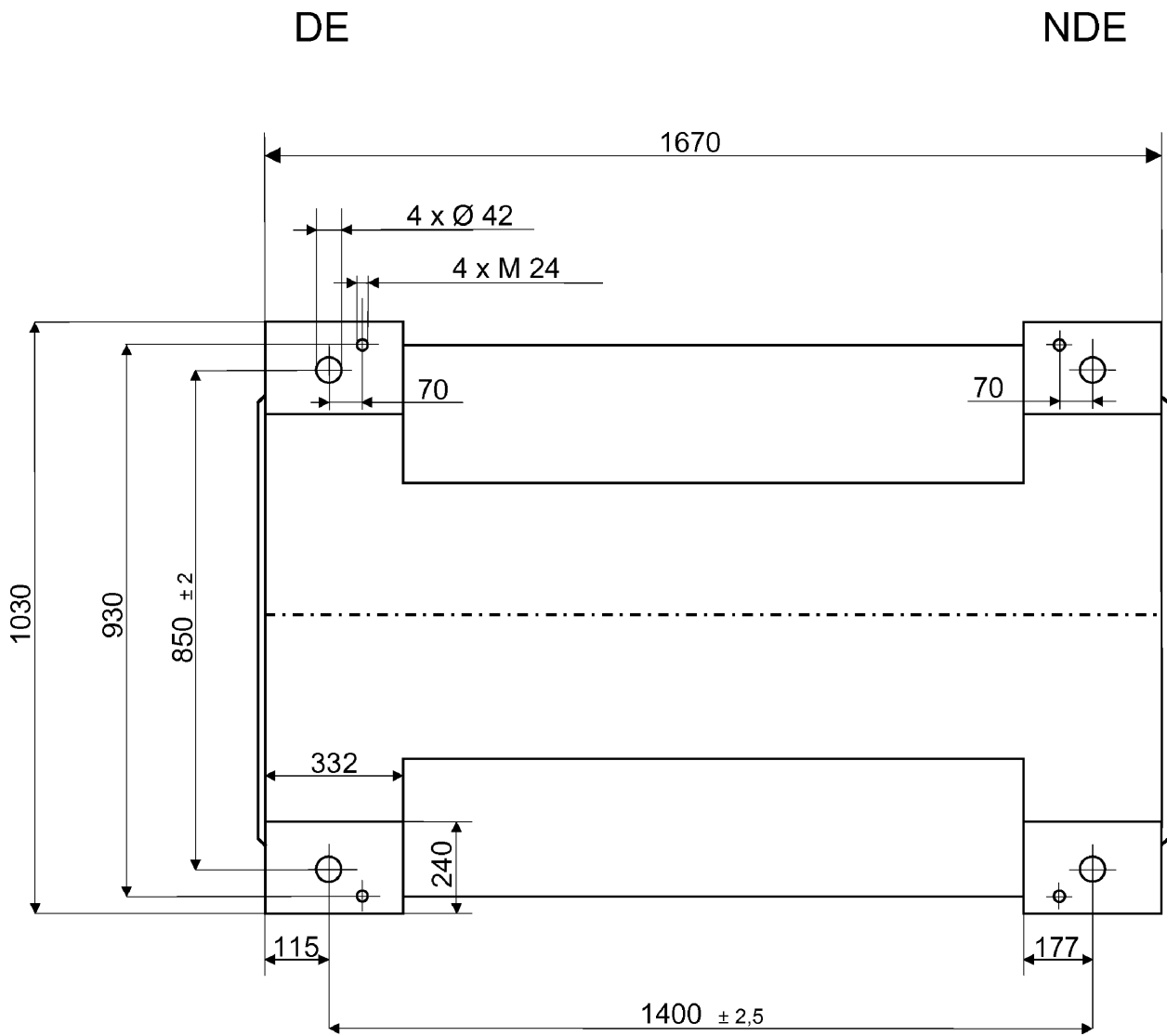
Dimension drawing position

22




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## 8 Footprint drawing



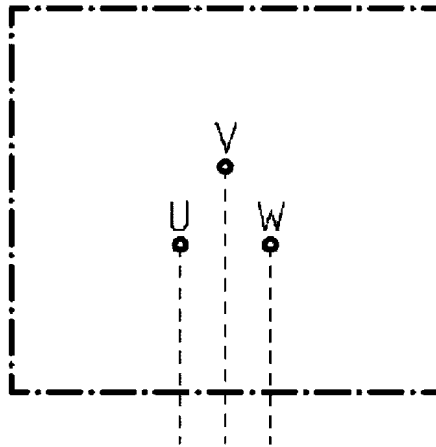
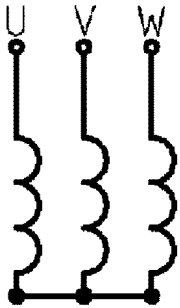
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## 9 Circuit diagrams/terminal diagrams

### 9.1 Circuit diagram Stator line connection

Dimension drawing position 1



 Schaltung  
Connection



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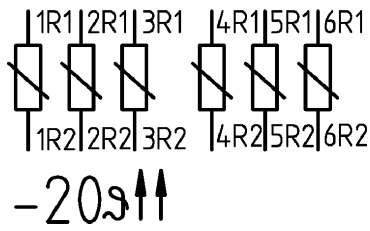
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## 9.2 Terminal diagram Auxiliary circuits

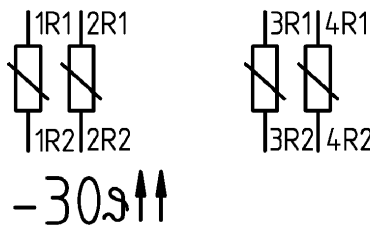
Dimension drawing position

3

Terminal strip - X1		Link	Term.No.	Destination/ Item designation	
A	○	●	PE	c	
B	○	●	PE	c	
4	I	S	8	-20:1R1	
3			7		
2			6		
1			5	-20:1R2	
4	I	S	8	-20:2R1	
3			7		
2			6		
1			5	-20:2R2	
4	I	S	8	-20:3R1	
3			7		
2			6		
1			5	-20:3R2	
A	○	●	13	c	-20:4R1
B	○	●	14	c	-20:4R2
A	○	●	15	c	-20:5R1
A	○	●	16	c	-20:5R2
A	○	●	17	c	-20:6R1
A	○	●	18	c	-20:6R2
A	○	●	19	c	
A	○	●	20	c	
4	I	S	8	-30:1R1	
3			7		
2			6		
1			5	-30:1R2	
4	I	S	8	-30:3R1	
3			7		
2			6		
1			5	-30:3R2	
A	○	●	29	c	-30:2R1
A	○	●	30	c	-30:2R2
A	○	●	31	c	-30:4R1
A	○	●	32	c	-30:4R2
A	○	●	33	c	
A	○	●	34	c	
A	○	●	35	c	
A	○	●	PE	c	



Slot thermometer  
Nut-Thermometer



DE D-Seite NDE N-Seite  
Bearing thermometer  
Lager-Thermometer

Test voltage max. 5V for PTC or NTC thermistors,  
thermo couples or resistance thermometers  
Prüfspannung max. 5V bei Kalt-, Heißleitern,  
Thermoelementen u. Widerstandsthermometern.

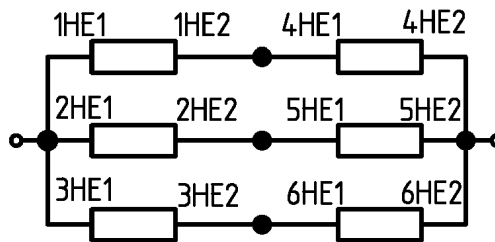
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### 9.3 Terminal diagram Anti-condensation heating

Dimension drawing position

5

Terminal strip - X2			Destination/ Item designation	
	Link	Term.No.	A	B
⌋ ●	●	PE	A	B
⌋ ●	●	1	A	B
⌋ ●	●	2	A	B
⌋ ●	●	3	A	B
⌋ ●	●	4	A	B
⌋ ●	●	5	A	B
⌋ ●	●	6	A	B
⌋ ●	●	7	A	B
⌋ ●	●	8	A	B



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Anti-condensation heater  
Stillstandsheizung



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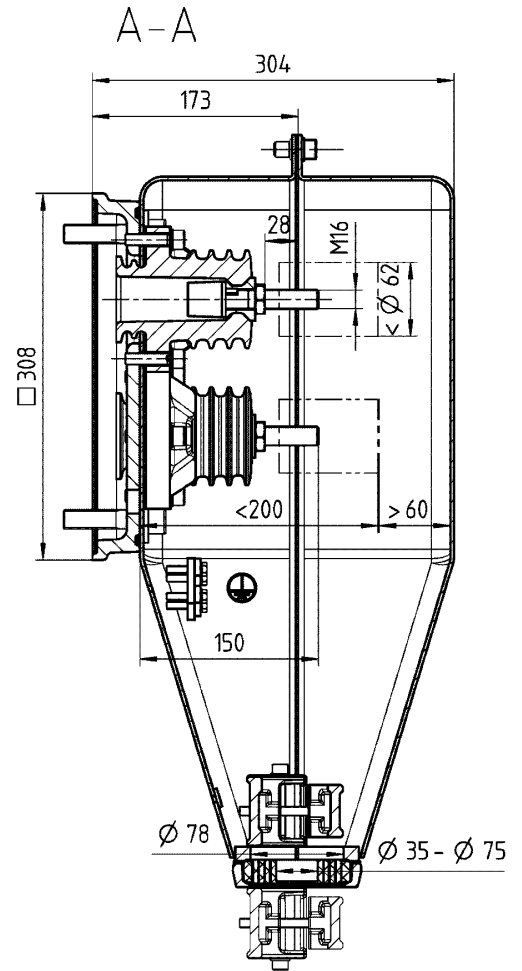
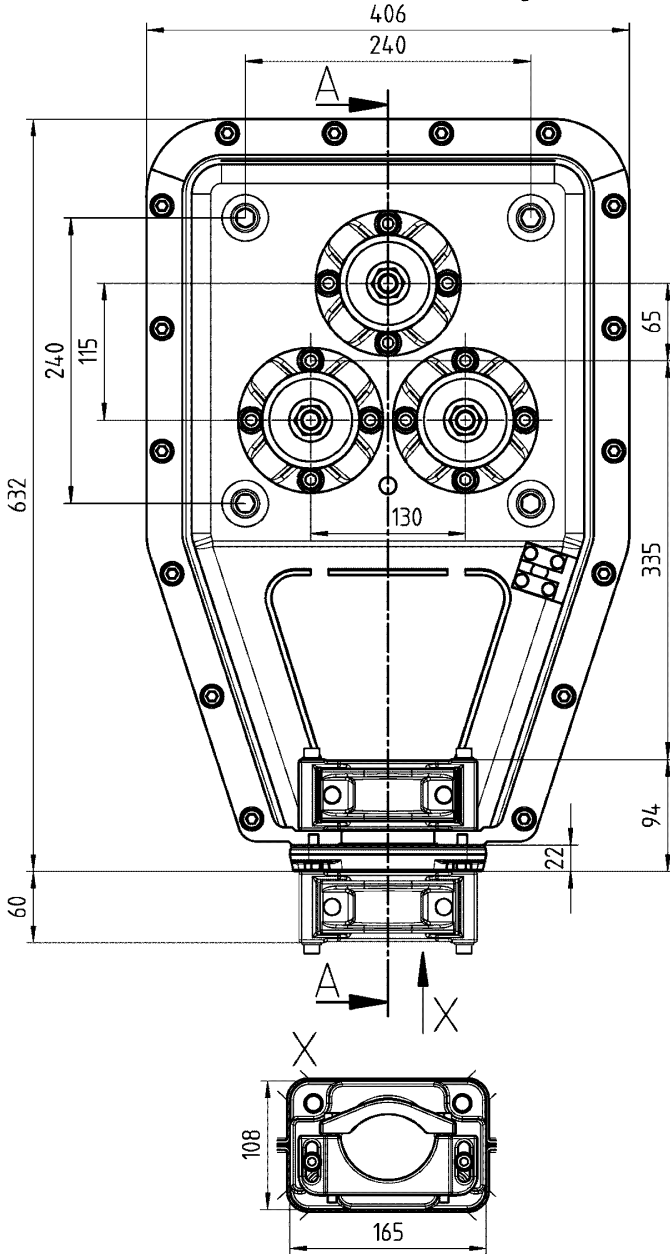
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**10 Dimension drawings, terminal box**  
**10.1 Terminal box Stator line connection**  
 Dimension drawing position 1

Shown without terminal box cover  
 Ohne Klemmenkastendeckel dargestellt



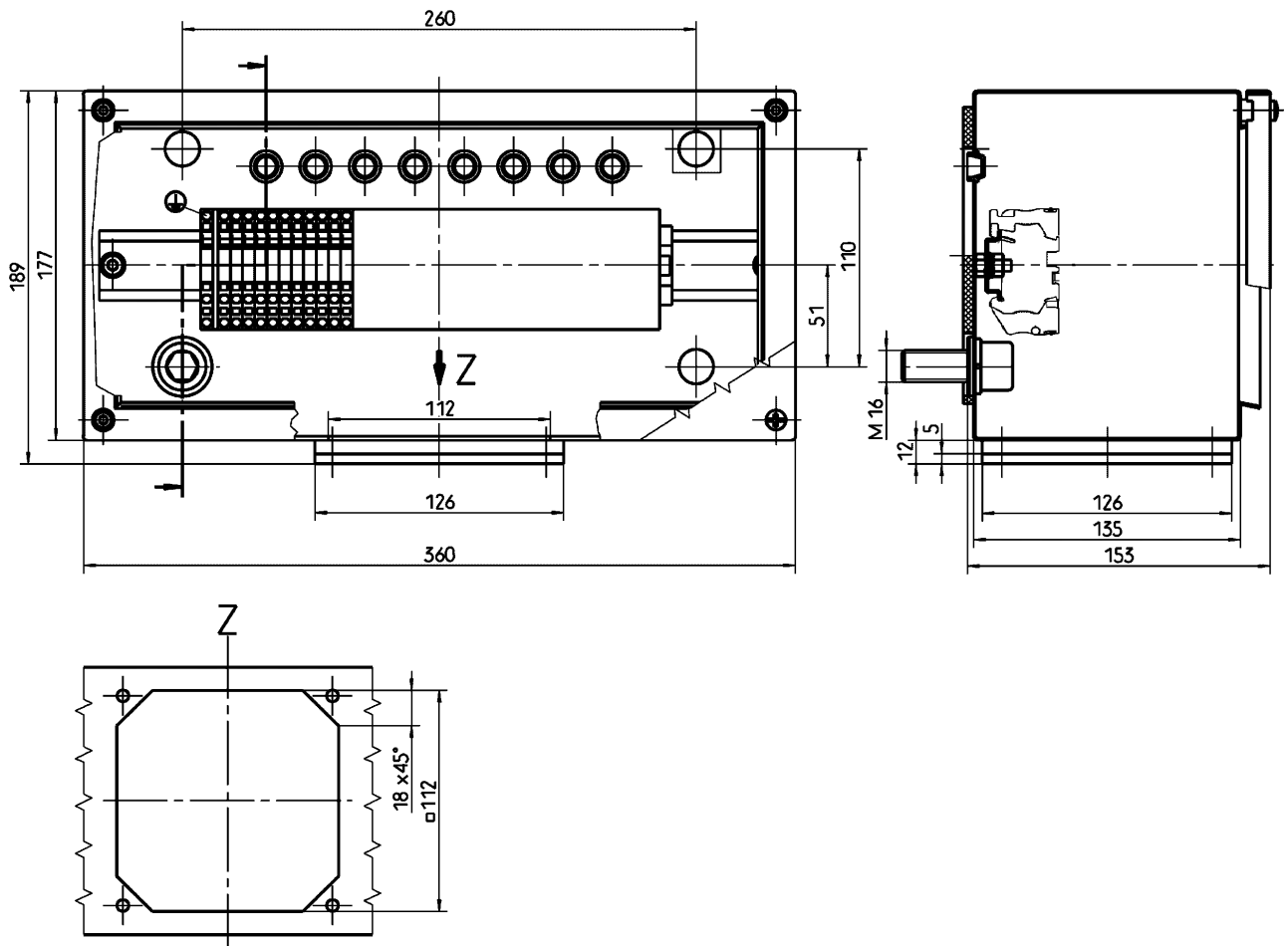
CT for Differential protection?


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## 10.2 Terminal box Auxiliary circuits

Dimension drawing position

3



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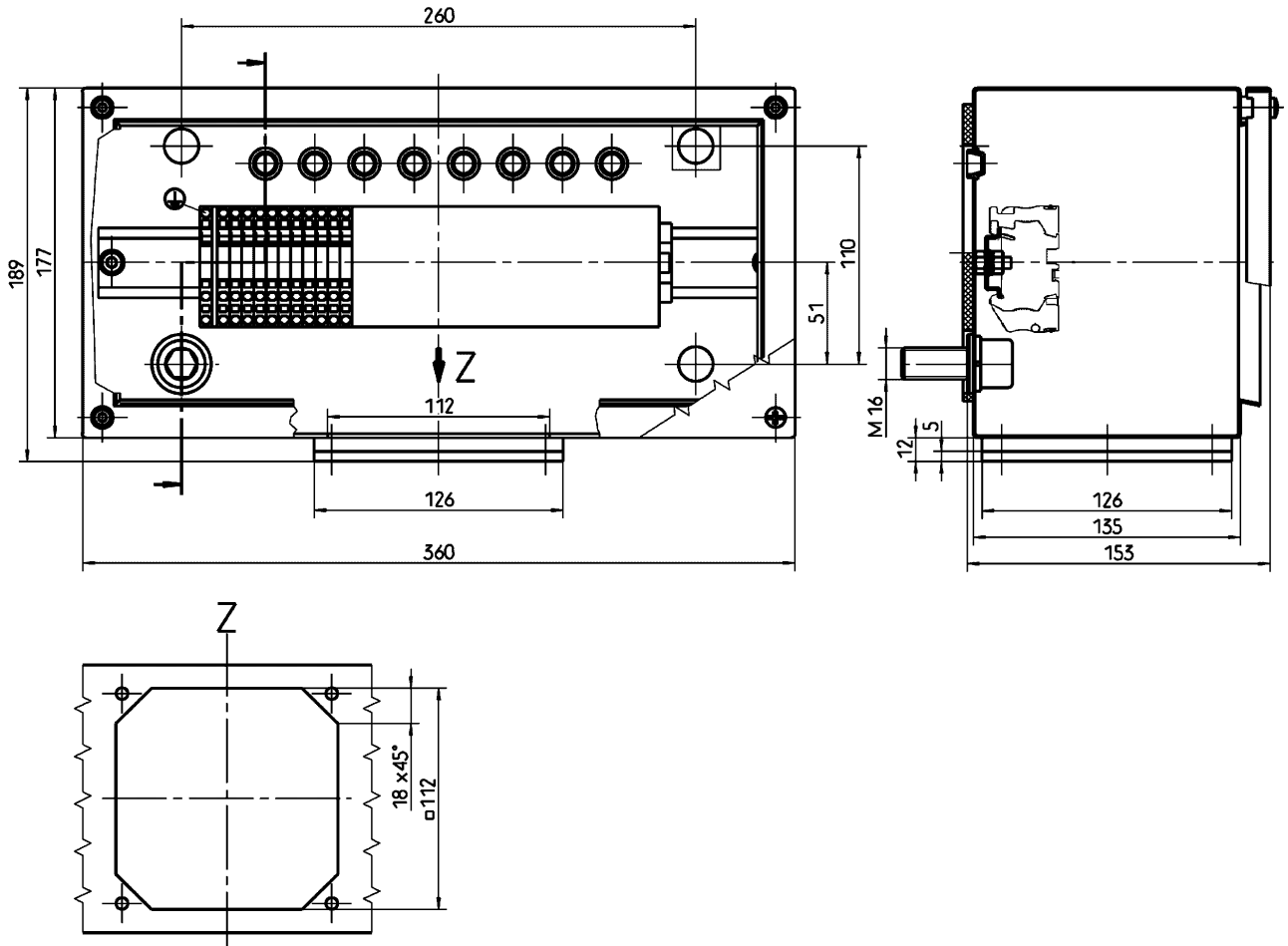
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### 10.3 Terminal box Anti-condensation heating

Dimension drawing position 5



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